

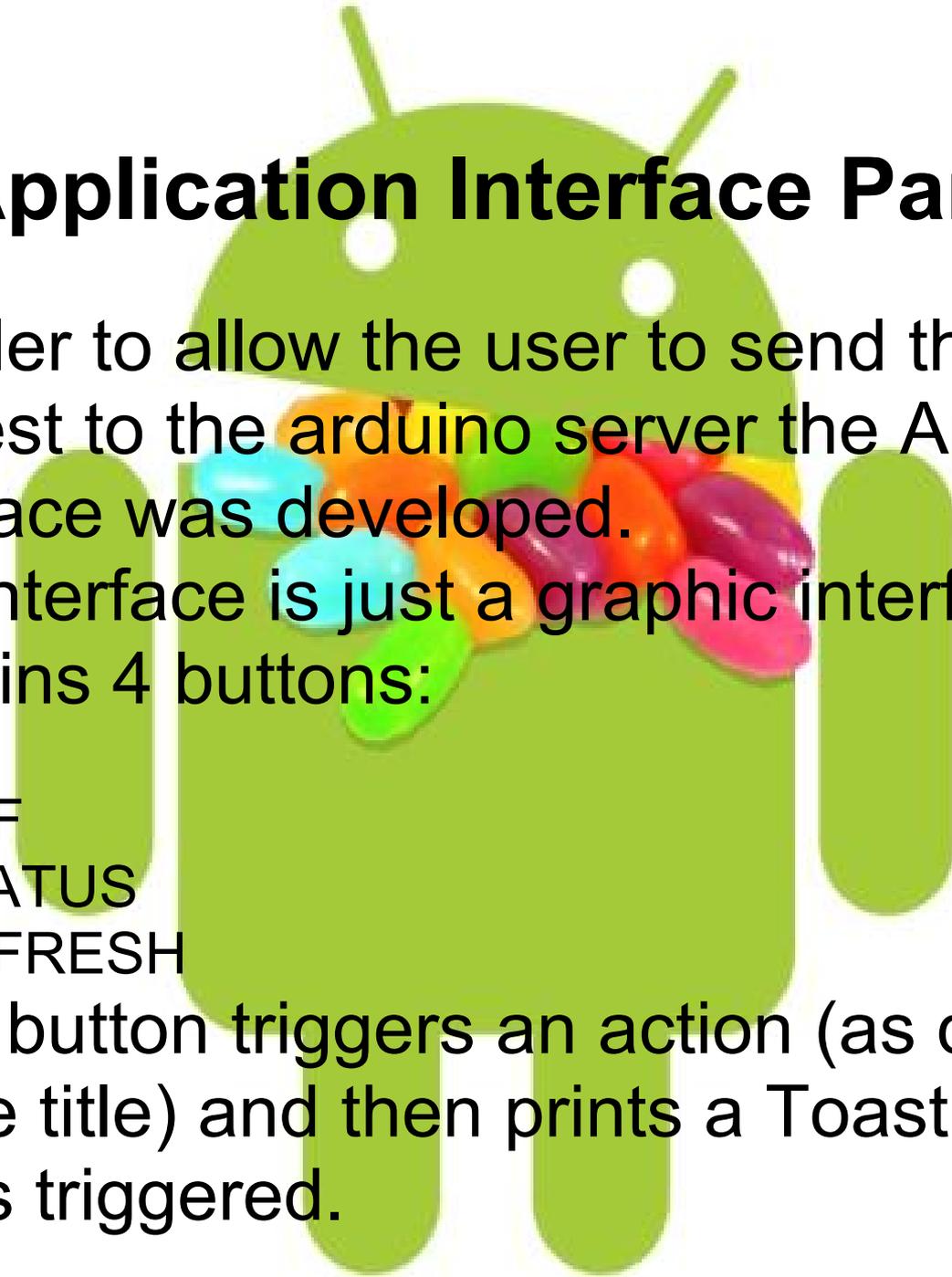
# Automate your tasks using Arduino and Android



Presented By:

- Kaponis Georgios(Kaponakis)
- Mageirias Anastasios(mag)
- Karastathis Vaios(vKaras)
- Boviatsis Dimitrios

# Application Interface Part

A green Android robot is centered in the background. It has two antennae on its head and a large, rounded body. On its chest, there is a cluster of colorful jelly beans in shades of blue, orange, red, yellow, and purple.

- In order to allow the user to send the http request to the arduino server the Application Interface was developed.
- The interface is just a graphic interface that contains 4 buttons:
  - ON
  - OFF
  - STATUS
  - REFRESH
- Each button triggers an action (as described by the title) and then prints a Toast about the status triggered.

# Application Interface Part

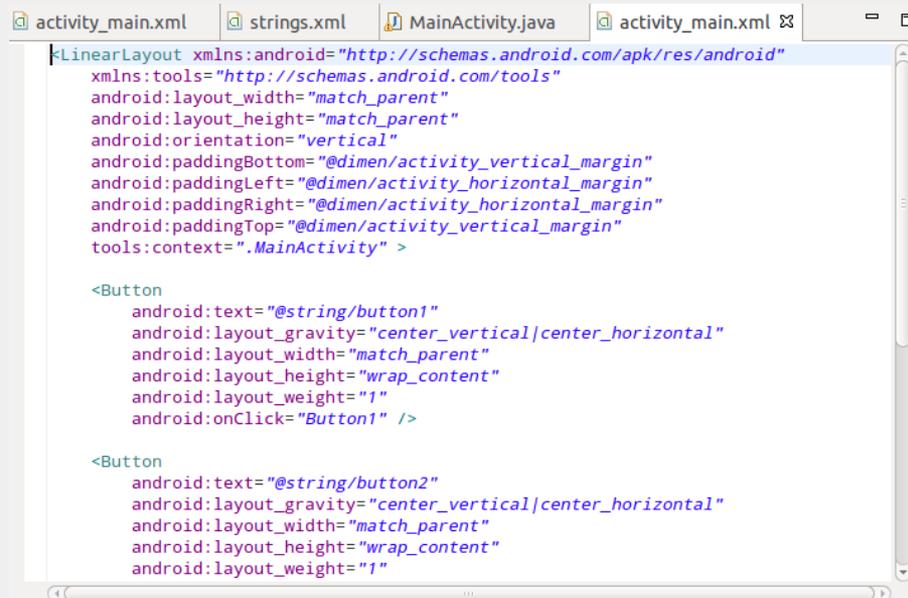
After triggering the status button a toast appears and shows you the current status such as connection and led.

## Code Explanation

Basically an xml file is modified. An xml file contains all the resources that the main activity is going to use such as buttons and strings. Then we modify the main activity so that by clicking the button another action is triggered.

# Code Explanation

The xml file as seen on Eclipse IDE

A screenshot of the Eclipse IDE interface. The top toolbar shows four tabs: 'activity\_main.xml', 'strings.xml', 'MainActivity.java', and 'activity\_main.xml'. The active tab is the rightmost 'activity\_main.xml'. The main editor area displays the XML code for the activity layout. The code defines a LinearLayout with vertical orientation and match\_parent dimensions, containing two buttons. The first button is centered and has a text reference to '@string/button1'. The second button is also centered and has a text reference to '@string/button2'.

```
<LinearLayout xmlns:android="http://schemas.android.com/apk/res/android"
    xmlns:tools="http://schemas.android.com/tools"
    android:layout_width="match_parent"
    android:layout_height="match_parent"
    android:orientation="vertical"
    android:paddingBottom="@dimen/activity_vertical_margin"
    android:paddingLeft="@dimen/activity_horizontal_margin"
    android:paddingRight="@dimen/activity_horizontal_margin"
    android:paddingTop="@dimen/activity_vertical_margin"
    tools:context=".MainActivity" >

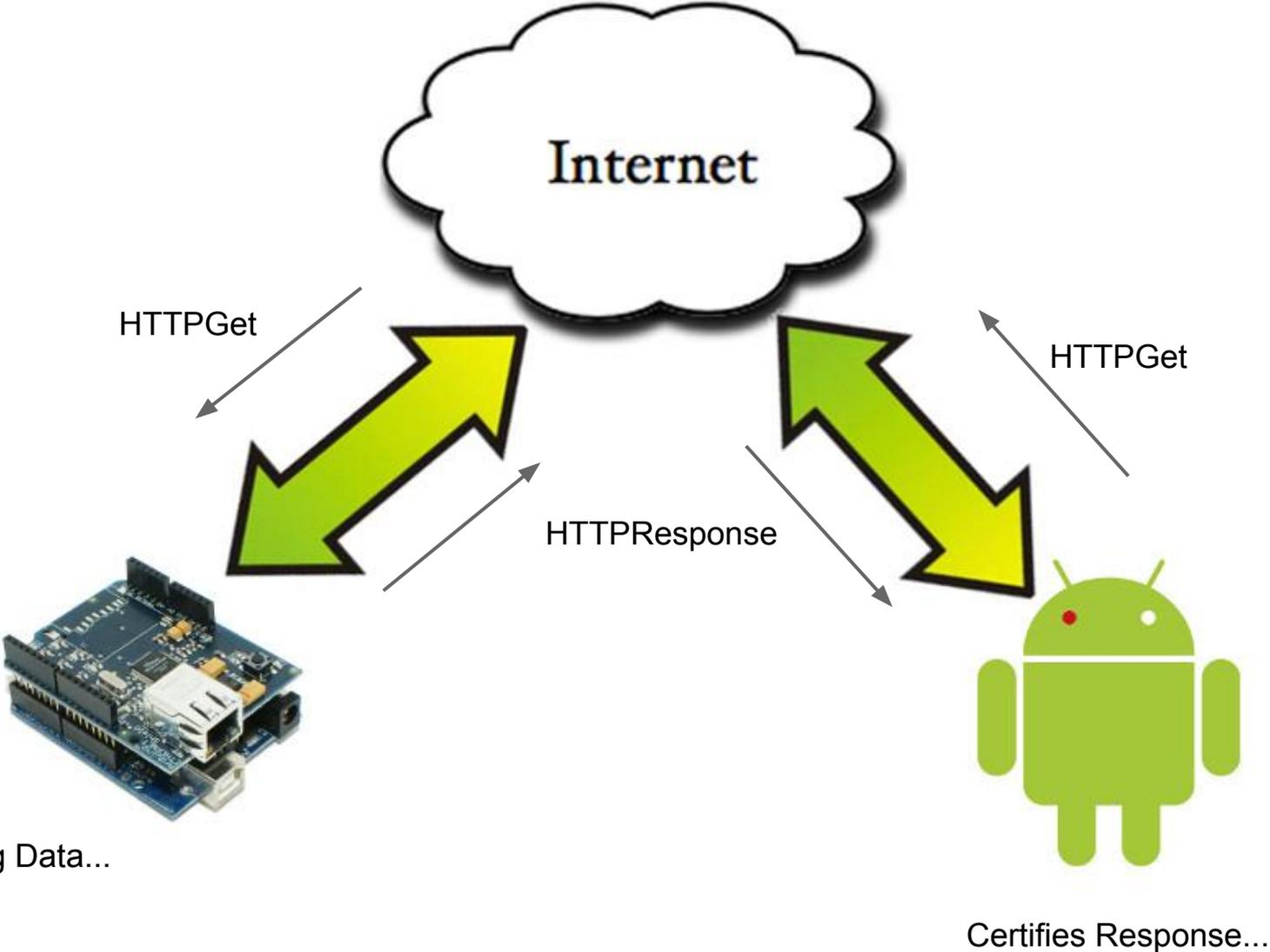
    <Button
        android:text="@string/button1"
        android:layout_gravity="center_vertical|center_horizontal"
        android:layout_width="match_parent"
        android:layout_height="wrap_content"
        android:layout_weight="1"
        android:onClick="Button1" />

    <Button
        android:text="@string/button2"
        android:layout_gravity="center_vertical|center_horizontal"
        android:layout_width="match_parent"
        android:layout_height="wrap_content"
        android:layout_weight="1"
```

# Android Networking Part

- Arduino communicates with android via HTTP requests, using ethernet shield.
- As an Http Client we used Apache Http Client instead of HttpURLConnection, because it has fewer bugs on Eclair (API Level 7) and on earlier versions.
- We used HTTP GET requests because it was easier both for android and arduino development (it can also be accomplished with POST requests)
- So we send certain predefined HTTP GET requests (pressing buttons) to Arduino, ordering it to execute some snippets of code.

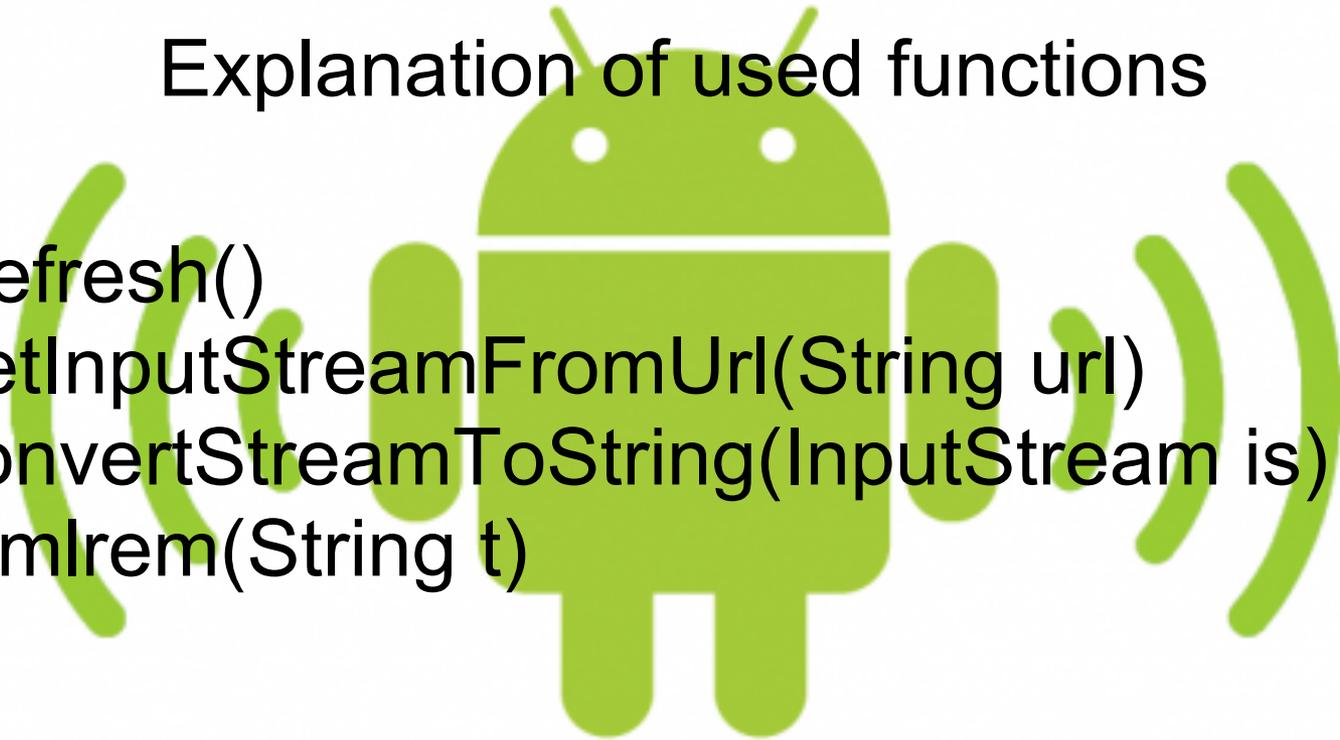
# Android - Arduino Communication



# Android Networking Part

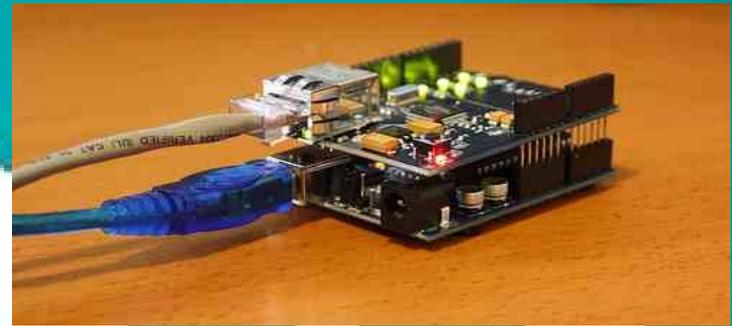
Explanation of used functions

- Refresh()
- `getInputStreamFromUrl(String url)`
- `convertStreamToString(InputStream is)`
- `htmlrem(String t)`



# Programming Arduino Part

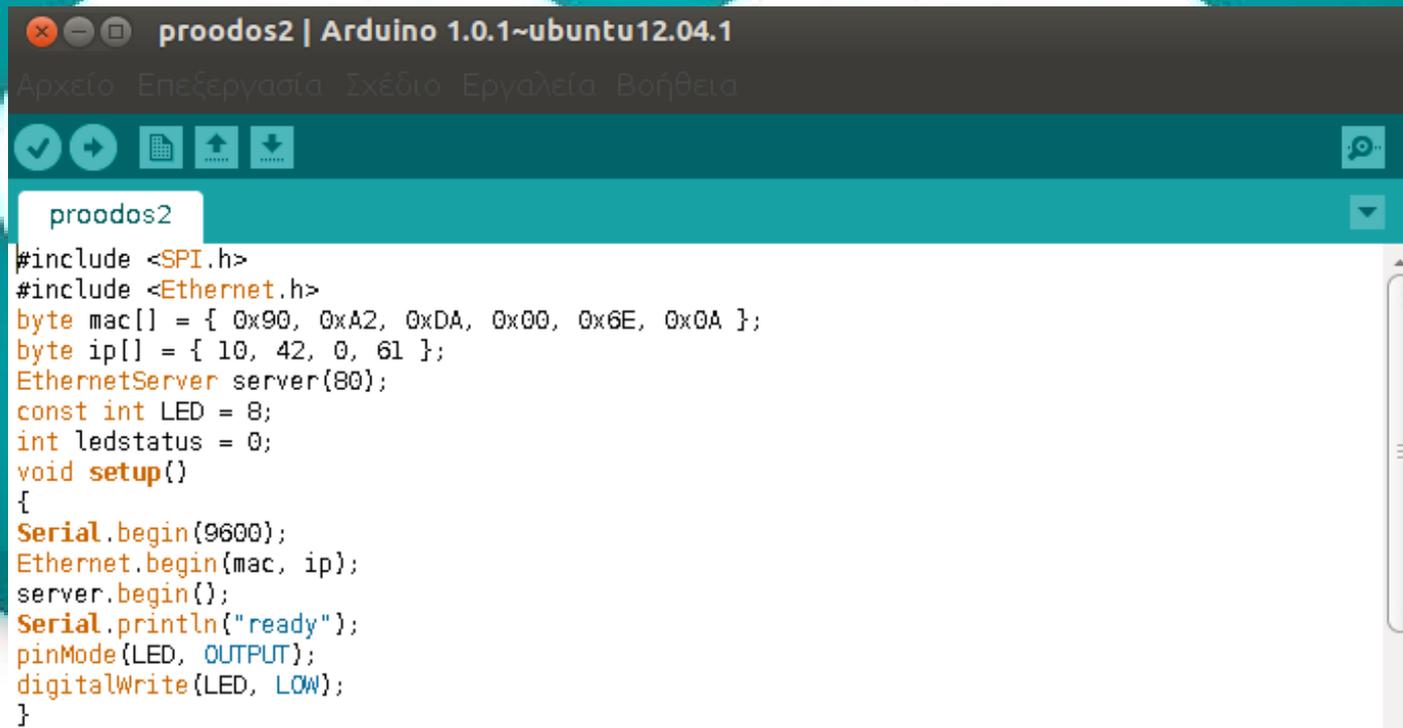
- In order to give arduino the chance to receive commands from internet we hook it up with the ethernet shield :



- Then, we start a server at the shield

that is running at port 80 (the default port for the http requests).

- As mentioned previously, this server is handling 'GET' requests.
- The code as seen on Arduino IDE:



```
proodos2 | Arduino 1.0.1~ubuntu12.04.1
Αρχείο Επεξεργασία Σχέδιο Εργαλεία Βοήθεια
[Icons] [Search]
proodos2
#include <SPI.h>
#include <Ethernet.h>
byte mac[] = { 0x90, 0xA2, 0xDA, 0x00, 0x6E, 0x0A };
byte ip[] = { 10, 42, 0, 61 };
EthernetServer server(80);
const int LED = 8;
int ledstatus = 0;
void setup()
{
  Serial.begin(9600);
  Ethernet.begin(mac, ip);
  server.begin();
  Serial.println("ready");
  pinMode(LED, OUTPUT);
  digitalWrite(LED, LOW);
}
```

- In order to understand that the incoming request wants arduino to perform an action (turn the lamp 'ON', 'OFF' or return its current status) the prefix "pin" is used in the http request.
- After the prefix follows a number (0, 1 or 2).
- Each of these numbers corresponds to a specific action. 1 turns the lamp 'ON', 0 turns it 'OFF' and 2 returns its current status

```
if( val=='1' ) {  
    digitalWrite(LED, HIGH);  
    ledstatus = 1;  
}  
if( val=='0' ){  
    digitalWrite(LED, LOW);  
    ledstatus = 0;  
}
```

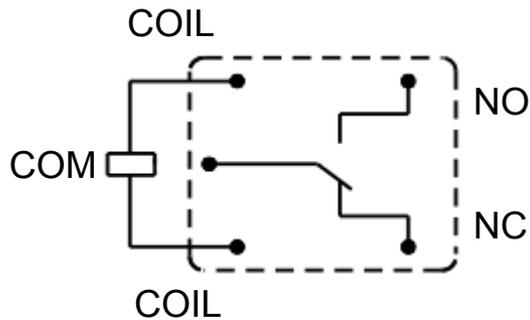
- In the final part of the code, the result is printed in html form.
- This type of response is used because it is easier for the Android App to read the reply.
- Here is the response code:

```
// send a standard http response header
client.println("HTTP/1.1 200 OK");
client.println("Content-Type: text/html");
client.println();
client.println(ledstatus);
client.println();
client.println("<br />");
client.println("<br />");
client.println();
```

# Using Arduino to Control Relays

So, what exactly is a relay?

- Coil
- Switch



# Materials

- Arduino Uno + Ethernet Shield
- Rectifier Diode 1N4004
- Relay SRD-S-106D
- Resistor 1k $\Omega$
- NPN Transistor 2N2222
- Work Lamp
- Insulating Tape

# Safety

- Employ an electrician
- Don't work with relay or extension cords while plug is connected to socket
- Enclose any wires before testing

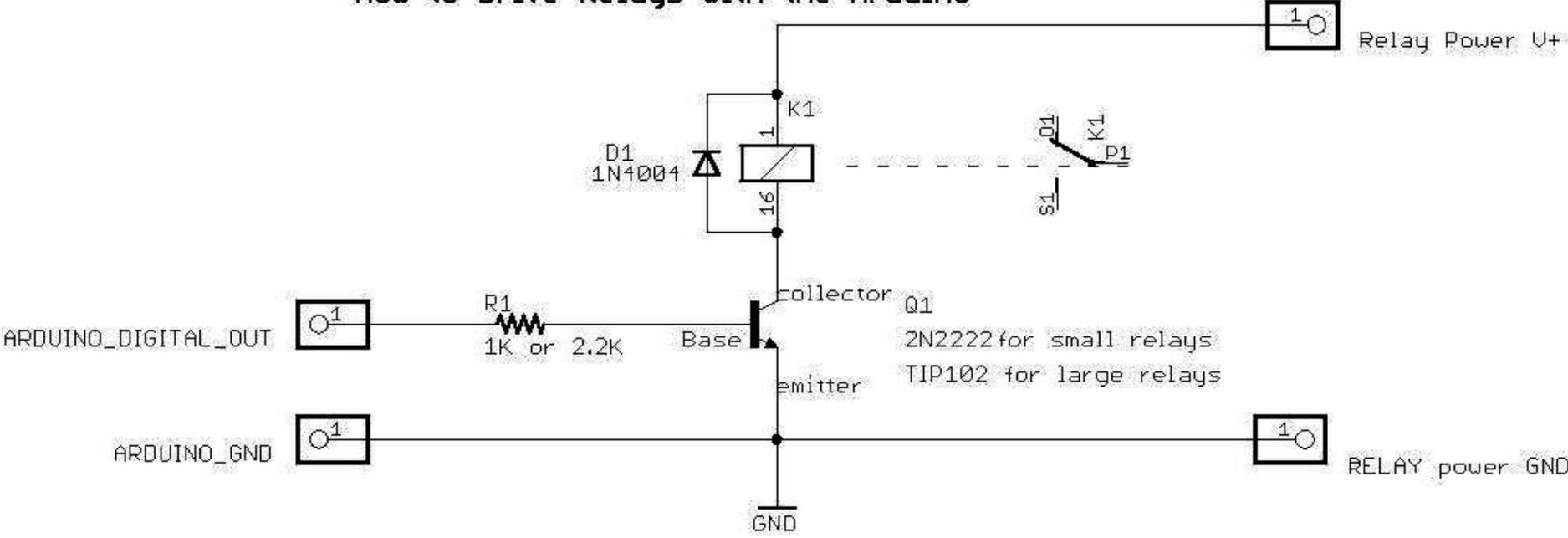


# Preparation

- Cut the cord in half
- Solder "active"(black or brown) wire with coil pins
- Solder the wires with the same color together
- Insulate properly

# Schematic

How to Drive Relays with the Arduino



# Putting it All Together

